ED II: Lecture 4

Time dependent EM fields: relaxation, propagation

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Electromagnetic waves
 Propagating plane wave
 Decaying plane wave





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 Stationary state, by definition, means that the currents are steady and there is no net charge movement, i.e.

$$abla \cdot \vec{\mathbf{J}}_s = 0 \quad \text{or} \quad \frac{\partial \rho}{\partial t} = 0$$
(1)

These statements are equivalent, due to continuity.

- If the initial distribution of charges and currents does not satisfy the above criteria, they will redistribute themselves so that a stationary state is reached.
- This process of "relaxation" happens over a time scale that is characteristic of the medium, called the relaxation time.

Relaxation time

• The continuity equation, combining with $\nabla \cdot \vec{\mathbf{D}} = \rho$, gives

$$\nabla \cdot \frac{\partial \vec{\mathbf{D}}}{\partial t} = -\nabla \cdot \vec{\mathbf{J}}$$
(2)

• Using $\vec{\mathbf{D}} = \epsilon \vec{\mathbf{E}}$ and $\vec{\mathbf{J}} = \sigma \vec{\mathbf{E}}$,

$$\nabla \cdot \left(1 + \frac{\epsilon}{\sigma} \frac{\partial}{\partial t}\right) \vec{\mathbf{J}} = 0 \tag{3}$$

The solution to this differential equation is

$$\vec{\mathbf{J}} = \vec{\mathbf{J}}_s + (\vec{\mathbf{J}}_0 - \vec{\mathbf{J}}_s)e^{-t/\tau}$$
(4)

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where J_0 is the initial current distribution

- $\tau = \epsilon / \sigma$ is the relaxation time
- $\frac{\partial \rho}{\partial t} = -\nabla \cdot \vec{J}$, $\vec{E} = \sigma \vec{J}$, etc. relax at the same rate.



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Time-dependent electric field

• No free charges, no external EMF sources. Maxwell \Rightarrow

$$\nabla \times (\nabla \times \vec{\mathbf{E}}) = -\frac{\partial}{\partial t} (\nabla \times \mu \vec{\mathbf{H}})$$
 (5)

$$\nabla(\nabla \cdot \vec{\mathbf{E}}) - \nabla^2 \vec{\mathbf{E}} = -\mu \frac{\partial}{\partial t} (\vec{\mathbf{J}}_{\rm fr} + \epsilon \frac{\partial \vec{\mathbf{E}}}{\partial t})$$
(6)

This gives the second order partial differential equation

$$\nabla^2 \vec{\mathbf{E}} - \mu \sigma \frac{\partial \vec{\mathbf{E}}}{\partial t} - \mu \epsilon \frac{\partial^2 \vec{\mathbf{E}}}{\partial t^2} = \mathbf{0}$$
 (7)

• Depending on whether the $(\partial^2 \vec{E}/\partial t^2)$ term dominates or the $(\partial \vec{E}/\partial t)$ one, we'll get two different extremes of behaviour. The former will lead to a propagating wave, the latter will lead to a diffusion equation, corresponding to a decaying wave.

Looking for solution of the form $\vec{E}(\vec{x})e^{-i\omega t}$

The differential equation becomes

$$\nabla^2 \vec{\mathbf{E}} + \mu \epsilon \omega^2 (1 + \frac{i\sigma}{\epsilon\omega}) \vec{\mathbf{E}} = 0$$
(8)

• There are two time scales here: 1/ ω and $\tau = \epsilon/\sigma$

$$\nabla^2 \vec{\mathbf{E}} + \mu \epsilon \omega^2 (1 + \frac{i}{\tau \omega}) \vec{\mathbf{E}} = 0$$
(9)

(10)

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• When $\tau \omega >> 1$, $\nabla^2 \vec{\mathbf{E}} + \mu \epsilon \omega^2 \vec{\mathbf{E}} = 0$

which is a wave propagating with speed $c=1/\sqrt{\mu\epsilon}$

• When $\tau \omega << 1$, $\nabla^2 \vec{\mathbf{E}} + \frac{i\omega}{\tau c^2} \vec{\mathbf{E}} = 0$ (11)

which is the equation for diffusion. In the context of EM waves, this will lead to a decaying solution.

• we shall explore these behaviours in detail now.



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Propagating (plane wave) solution for \vec{E}

• $\omega \tau >> 1 \Rightarrow$ displacement current dominates over conduction current

$$\nabla^2 \vec{\mathbf{E}} + \mu \epsilon \omega^2 \vec{\mathbf{E}} + i \omega \mu \sigma \vec{\mathbf{E}} = 0$$
 (12)

- Plane wave: all fields are functions of the distance ζ of a plane from the origin. n̂ is the normal to this plane.
- $\nabla \rightarrow \hat{\mathbf{n}}(\partial/\partial \zeta)$
- Maxwell's equations in this language:

$$\hat{\mathbf{n}} \cdot \frac{\partial \vec{\mathbf{D}}}{\partial \zeta} = \mathbf{0} , \qquad \hat{\mathbf{n}} \times \frac{\partial \vec{\mathbf{E}}}{\partial \zeta} = -\frac{\partial \vec{\mathbf{B}}}{\partial t}$$
(13)
$$\hat{\mathbf{n}} \cdot \frac{\partial \vec{\mathbf{B}}}{\partial \zeta} = \mathbf{0} , \qquad \hat{\mathbf{n}} \times \frac{\partial \vec{\mathbf{H}}}{\partial \zeta} = \frac{\partial \vec{\mathbf{D}}}{\partial t}$$
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Longitudinal components of \vec{E} and \vec{B}

\vec{E}_{\parallel} : longitudinal component of \vec{E}

• $(\partial \vec{\mathbf{D}} / \partial \zeta)$ equation and dot product of $\hat{\mathbf{n}}$ with the $(\partial \vec{\mathbf{H}} / \partial \zeta)$ equation \Rightarrow

$$\frac{\partial \vec{\mathbf{E}} \cdot \hat{\mathbf{n}}}{\partial \zeta} = 0 , \quad \frac{\partial \vec{\mathbf{E}} \cdot \hat{\mathbf{n}}}{\partial t} = 0$$
 (15)

• For non-conducting media (e.g. vacuum), \vec{E}_{\parallel} is a constant.

Longitudinal component of \vec{B}

• $(\partial \vec{\mathbf{B}} / \partial \zeta)$ equation and dot product of $\hat{\mathbf{n}}$ with the $(\partial \vec{\mathbf{E}} / \partial \zeta)$ equation \Rightarrow

$$\frac{\partial \vec{\mathbf{B}} \cdot \hat{\mathbf{n}}}{\partial \zeta} = 0 , \quad \frac{\partial \vec{\mathbf{B}} \cdot \hat{\mathbf{n}}}{\partial t} = 0$$
(16)

 Only stationary longitudinal component of **B** is possible, i.e. **B**_{||} is constant (note: we have taken μ = μ₀)

Transverse components of \vec{E} and \vec{B}

• Combining the two $\hat{\boldsymbol{n}}\times$ equations:

$$\hat{\mathbf{n}} \times (\frac{\partial^2 \vec{\mathbf{E}}}{\partial \zeta^2} - \mu \epsilon \frac{\partial^2 \vec{\mathbf{E}}}{\partial t^2}) = 0$$
(17)

- Differential equation for $\vec{\textbf{E}}_{\perp}=\vec{\textbf{E}}\times\hat{\textbf{n}}$
- General solution: $\vec{\mathbf{E}}_{\perp} = \vec{\mathbf{E}}_{\perp,0}[f(\zeta ut) + g(\zeta + ut)]$
- If \vec{E}_{\perp} is sinusoidal:

$$\vec{\mathsf{E}}_{\perp} = \vec{\mathsf{E}}_{\perp,0} e^{-i(\omega t \pm k\zeta)} \tag{18}$$

• Direction of propagation $\vec{k} \Rightarrow$

$$\vec{\mathsf{E}}_{\perp} = \vec{\mathsf{E}}_{\perp,0} e^{i(\vec{\mathsf{k}}\cdot\vec{r}-\omega t)}$$
(19)

• Using $\hat{\mathbf{n}} \times (\partial \vec{\mathbf{E}}_{\perp} / \partial \zeta) = -\partial \vec{\mathbf{B}}_{\perp} / \partial t$,

$$i\vec{\mathbf{k}}\times\vec{\mathbf{E}}_{\perp}=i\omega\vec{\mathbf{B}}_{\perp}\Rightarrow\vec{\mathbf{B}}_{\perp}=\frac{\vec{\mathbf{k}}}{\omega}\times\vec{\mathbf{E}}$$
(20)

- \vec{E}_{\parallel} and \vec{B}_{\parallel} are constants in space and time, hence not interesting for wave propagation
- \vec{E}_{\perp} and \vec{B}_{\perp} can have $e^{i(\vec{k}\cdot\vec{r}-\omega t)}$ dependence, with $\vec{B}_{\perp} = (\vec{k}/\omega) \times \vec{E}$
- \vec{E} and \vec{B} fields are transverse to the direction of motion, and also orthogonal to each other.

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Decaying plane wave

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Decaying plane wave

 When ωτ << 1, conduction current dominates over displacement current

$$\nabla^2 \vec{\mathbf{E}} + \mu \epsilon \omega^2 \vec{\mathbf{E}} + i \omega \mu \sigma \vec{\mathbf{E}} = 0$$
 (21)

• The solution of the form $\vec{\mathbf{E}}_0 e^{\pm i(kx-\omega t)}$ implies

$$k^{2} = -\frac{i\omega}{c^{2}\tau} = \frac{\omega}{c^{2}\tau} e^{-i\pi/2}$$
(22)
$$\Rightarrow k = \sqrt{\frac{\omega}{c^{2}\tau}} e^{-i\pi/4} = \sqrt{\frac{\omega}{c^{2}\tau}} \left(\frac{1-i}{\sqrt{2}}\right)$$
(23)

This gives

$$\vec{\mathsf{E}} = \vec{\mathsf{E}}_0 e^{\pm i(\operatorname{Re}(k)x - \omega t)} e^{-\operatorname{Im}(k)x}$$
(24)

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• The wave then decays with a $e^{-\text{Im}(k)x}$ dependence inside the conducting medium.

Skin depth in metals

- For metals, τ ~ 10⁻¹⁴ sec. So for ω < 10¹⁴, conduction current dominates.
- A wave incident on a metallic surface will decay as

$$\vec{\mathsf{E}}| = |\vec{\mathsf{E}}_0| e^{-r/\delta} \tag{25}$$

where, from the last page, (check factor of 2)

$$\delta = \sqrt{\frac{2c^2\tau}{\omega}} = \sqrt{\frac{2}{\sigma\omega}}$$
(26)

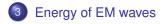
 Within a distance δ from the surface of the metal, the wave would decrease in magnitude by a factor 1/e. This δ is the "skin depth" of the metal. The surface currents will flow within this width.

• "Ideal" conductor
$$\Rightarrow \delta \rightarrow 0$$
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Quadratic quantities and factors of 2

• In Electrodynamics, for convenience, we often use notation involving complex numbers (mainly exponentials), e.g.

$$\vec{\mathbf{E}} = \vec{\mathbf{E}}_0 e^{i(kx-\omega t)} , \quad \vec{\mathbf{B}} = -i\vec{\mathbf{B}}_0 e^{i(kx-\omega t)}$$
(27)

when we actually want to represent

$$\vec{\mathsf{E}} = \vec{\mathsf{E}}_0 \cos(kx - \omega t) = \operatorname{Re}(\vec{\mathsf{E}}_0 e^{i(kx - \omega t)})$$
(28)

$$\vec{\mathbf{B}} = \vec{\mathbf{B}}_0 \sin(kx - \omega t) = \operatorname{Re}(i\vec{\mathbf{B}}_0 e^{i(kx - \omega t)})$$
(29)

- While performing calculations in complex notation and taking the real part of the final answer works as long as we are dealing with quantities linear in **Ē** or **B**, one has to be careful while dealing with quadratic (or higher order) quantities.
- For example, in the complex notation above,

$$\langle |\vec{\mathbf{E}}|^2 \rangle = \langle |\vec{\mathbf{E}}^* \cdot \vec{\mathbf{E}}| \rangle = |\vec{\mathbf{E}}_0|^2$$
 (30)

while the actual answer should be (using real notation)

$$\langle |\vec{\mathbf{E}}|^2 \rangle = |\vec{\mathbf{E}}_0|^2 \langle \cos^2(kx - \omega t) \rangle = \frac{1}{2} |\vec{\mathbf{E}}_0|^2 \tag{31}$$

Energy density stored in EM fields

• We have already seen that the energy stored in electric field is $U_e = (1/2)\epsilon_0 |\vec{\mathbf{E}}|^2$ (we showed this result for a static field). When the electric field represents a propagating wave, then taking into account the "factor of 2" for averaged quadratic quantities, we get

$$\langle U_e \rangle = \frac{1}{4} \epsilon_0 |\vec{\mathbf{E}}_0|^2$$
 (32)

• The energy stored in magnetic field is $U_m = (1/2)|\vec{\mathbf{B}}|^2/\mu_0$ (we showed it for a static magnetic field). For a propagating wave, $|\vec{\mathbf{B}}| = |\vec{\mathbf{k}}/\omega||\vec{\mathbf{E}}|$. Including the "factor of 2", we get

$$\langle U_m \rangle = \frac{1}{4} \frac{|\vec{\mathbf{B}}_0|^2}{\mu_0} = \frac{1}{4} \frac{|\vec{\mathbf{k}}|^2}{\omega^2 \mu_0} |\vec{\mathbf{E}}_0|^2 = \frac{1}{4} \epsilon_0 |\vec{\mathbf{E}}_0|^2$$
(33)

• For a plane EM wave, energy stored in electric and magnetic field is equal. The total energy of an EM wave is

$$\langle U \rangle = \langle U_e \rangle + \langle U_m \rangle = \frac{1}{2} \epsilon_0 |\vec{\mathbf{E}}_0|^2 \tag{34}$$

Energy transported by the EM fields

The rate of energy transport is given by the Poynting vector,

$$\vec{\mathsf{N}} = \vec{\mathsf{E}}^* \times \vec{\mathsf{H}}$$
 (35)

The time-averaged value of this quantity is

$$\langle |\vec{\mathbf{N}}| \rangle = \frac{1}{2} |\vec{\mathbf{E}}_{0}^{*}| |\vec{\mathbf{H}}_{0}| = \frac{1}{2} |\vec{\mathbf{E}}_{0}^{*}| \frac{|\vec{\mathbf{k}}|}{\omega \mu} |\vec{\mathbf{E}}_{0}| = \frac{1}{2} \sqrt{\frac{\epsilon_{0}}{\mu_{0}}} |\vec{\mathbf{E}}_{0}|^{2}$$
(36)

- Compared with the rate of energy consumption in a conductor, $(1/2)\sigma |\vec{\mathbf{E}}_0|^2$, the quantity $\sqrt{\epsilon_0/\mu_0}$ is termed the conductance of vacuum
- Similarly, $\sqrt{\epsilon/\mu}$ is the conductance of a medium through which an EM wave propagates
- Note that $\langle |\mathbf{N}| \rangle = c \langle U \rangle$, since the wave transports energy at the speed *c*.

Recap of topics covered in this lecture

- Relaxation to stationary state, relaxation time
- Electromagnetic wave: displacement current and conduction current
- Transverse electromagnetic field solutions for a propagating wave

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- Decay of EM waves in a condunctor, skin depth
- Energy stored and transported by an EM wave