The earth provides a non-inertial frame

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Classical Mechanics 2011 August 4, 2011 In an inertial frame a particle moving without forces on it will obey the composition laws $\mathbf{v}' = \mathbf{v} + \mathbf{V}_f$ and $\mathbf{x}' = \mathbf{x} + \mathbf{v}'t$. Finding whether a frame is non-inertial involves testing these laws.

How close to inertial is an earth-fixed frame?

We know that the motion of a particle near the earth is strongly non-inertial in the vertical direction, since everything falls. So the question is refined to examining motion in the horizontal directions. Since the earth rotates rigidly around a north-south axis, an earth-fixed frame will have different east-west velicities at different latitudes. The question is about the level of accuracy needed to detect this.

Scales of the problem

First restrict ourselves to displacements $|\mathbf{x}|$ which are much smaller than the radius of the earth, R_E . As long as $\delta = |\mathbf{x}|/R_E \ll 1$ the curvature of the earth's surface can be neglected, and the geometric and dynamic effects can be separated. We may take $|\mathbf{x}| \simeq 1$ Km, so that $\delta \simeq 10^{-4}$. The earth's rotational speed is $v_E = 2\pi R_E \cos \theta / T_D$ where θ is the latitude and $T_D = 86400$ s is the length of the day (*i.e.*, $T_D \simeq 100$ Ks). The rotational speed at the equator is $V_E^E = 2\pi R_E / T_D \simeq 1$ Km/s.

North-south (NS) motion clearly shows non-inertial effects through Coriolis acceleration, *i.e.*, the apparent deflection of the particle in the east-west (EW) direction. EW motion at two latitudes can be compared to detect non-inertial effects.

Experiments near the earth



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Particle 1 at latitude θ , sees the earth's tangential velocity as $v_1^E = V_E^E \cos \theta$; particle 2 at $\theta + \Delta \theta$ sees $v_2^E = v_1^E + V_E^E \Delta \theta \sin \theta$. The two particles start with the same initial velocities and separated only by a NS distance

$$\Delta y = R_E \Delta \theta \sin \theta = V_E^E T_D / (2\pi) \Delta \theta \sin \theta.$$

The EW distance between them changes as $\Delta x = tV_E^E \Delta \theta \sin \theta$. A dimensionless measure of how big the non-inertial effects are is given by $\epsilon = \Delta x / \Delta y = 2\pi t / T_D$. The only controllable parameter is the duration of the experiment, t.

Typically, if the vertical component of the particle's displacement is about 1 Km, then $t \simeq 10$ s, and $\epsilon \simeq 10^{-3}$. So, in motions covering about a Km, the fact that the earth is not an inertial frame changes the motion by about 1 m.

North-South Motion

A particle is thrown in a NS direction, with velocity v and travels a distance $\Delta y = vT \ll R_E$. The EW deflection in a time interval between t and t + dt is $dtv_E(\theta)$, where v_E is the earth's tangential velocity at the latitude $\theta(t) = \theta_i + vt/R_E$. The net EW deflection is

$$\Delta x = \int_0^T dt v_E(\theta) = R_E\left(\frac{V_E^E}{v}\right) \int_{\theta_i}^{\theta_i + \Delta y/R_E} d\theta \cos \theta \simeq \frac{V_E^E}{v} \Delta y.$$

We can define $\epsilon = \Delta x / \Delta y = V_E^E / v$. This dimensionless number ϵ captures how non-inertial the frame is. Clearly, if the earth were not rotating, so that V_E^E vanished, so would ϵ .

Why does a slow moving particle show the earth's rotation better? To understand this, note that in the last expression in the displayed equation above, $\Delta y/v$ is just the time T over which we study the motion. When v decreases, T increases, and the rotation of the earth becomes more apparent.