

# Orbital angular momentum

Sourendu Gupta

TIFR Graduate School

Quantum Mechanics 1

September 29, 2008

- 1 Orbital angular momentum
- 2 The rigid rotor: a quantum top
- 3 References

# Outline

- 1 Orbital angular momentum
- 2 The rigid rotor: a quantum top
- 3 References

# Spherical harmonics

We construct the operators and the eigenfunctions of orbital angular momentum,  $\mathbf{L} = \mathbf{r} \times \mathbf{p}$ , in the Hilbert space of position eigenstates. Then the usual differential operator for  $\mathbf{p}$  can be used. Under the scaling  $\mathbf{r} \rightarrow \xi \mathbf{r}$ , one has  $\mathbf{p} \rightarrow \mathbf{p}/\xi$ , so that  $\mathbf{L}$  is independent of the scale of the radius,  $\xi$ . Hence in this problem one can set  $|\mathbf{r}| = 1$ , i.e., use the unit vector  $\hat{\mathbf{r}}$ . We will use  $\hat{r}_z = \cos \theta$  and  $\hat{r}_{\pm} = \hat{r}_x \pm i\hat{r}_y = \exp(\pm i\phi) \sin \theta$ . The spherical harmonics are defined as

$$Y_m^l(\hat{\mathbf{r}}) = \langle \hat{\mathbf{r}} | lm \rangle, \quad L^2 Y_m^l(\hat{\mathbf{r}}) = \hbar^2 l(l+1) Y_m^l(\hat{\mathbf{r}}), \quad L_z Y_m^l(\hat{\mathbf{r}}) = \hbar m Y_m^l(\hat{\mathbf{r}}).$$

These have completeness and orthonormality

$$|lm\rangle = \int d\Omega |\hat{\mathbf{r}}\rangle \langle \hat{\mathbf{r}} | lm \rangle, \quad \int d\Omega [Y_{m'}^l(\hat{\mathbf{r}})]^* Y_m^l(\hat{\mathbf{r}}) = \delta_{ll'} \delta_{mm'}.$$

Since  $Y_m^l(\theta, \phi) = Y_m^l(\theta, \phi + 2\pi)$ , one has integer values of  $m$ , and hence also of  $l$ .

# The highest weight eigenfunction

We use the raising and lowering operators

$$L_{\pm} = \pm \hbar z \left( \frac{\partial}{\partial x} \pm i \frac{\partial}{\partial y} \right) \mp \hbar (x \pm iy) \frac{\partial}{\partial z}.$$

The scalar representation must have  $L_i Y_0^0 = 0$ , i.e.,  $Y_0^0$  must be a constant. The normalization condition gives  $Y_0^0 = 1/\sqrt{4\pi}$ . Since  $\hat{\mathbf{r}}$  is a vector operator, one has

$$Y_{\pm l}^l \propto r_{\pm}^l Y_0^0 = c_l (\hat{r}_x \pm i \hat{r}_y)^l = c_l e^{\pm i l} (\sin \theta)^l.$$

The normalization condition is

$$1 = |c_l|^2 \int \frac{d\phi d(\cos \theta)}{4\pi} (\sin \theta)^{2l} = |c_l|^2 \frac{1}{2} \int_{-1}^1 dz (1 - z^2)^l.$$

A recursion can be used to evaluate the integral. The normalized function is

$$Y_l^l(\theta, \phi) = \frac{1}{2^l l!} \sqrt{\frac{(2l+1)!}{4\pi}} (\sin \theta)^l e^{i l \phi}.$$

# Using the ladder

Note that

$$\frac{\partial f(\hat{r}_z)}{\partial x_i} = \frac{1}{r^3}(-x_i z + r^2 \delta_{i3}) \frac{df(\hat{r}_z)}{d\hat{r}_z}, \quad \text{hence} \quad L_- f(\hat{r}_z) = \hbar \hat{r}_- \frac{df(\hat{r}_z)}{d\hat{r}_z}.$$

Also, note that  $[L, \hat{r}_-] = 0$ . Now starting from

$$\hat{r}_-^l Y_l^l = c_l (1 - \hat{r}_z)^l, \quad \text{one finds} \quad \hat{r}_-^l L_-^N Y_l^l = c_l (\hbar \hat{r}_-^N) \frac{d^N}{d\hat{r}_z^N} (1 - \hat{r}_z)^l,$$

by applying  $L_-^N$  on both sides. Then, since

$$L_-^N Y_l^l = \hbar^N \sqrt{\frac{(2l)!N!}{(2l-N)!}} Y_{l-N}^l,$$

one finds all the spherical harmonics by the above recursion. This can also be done starting from the lowest weight representation and using  $L_+^N$ .

Comparing these two gives

$$Y_m^l(-\hat{\mathbf{r}}) = (-1)^l Y_m^l(\hat{\mathbf{r}}), \quad Y_{-m}^l(\hat{\mathbf{r}}) = (-1)^m [Y_m^l(\hat{\mathbf{r}})]^*.$$

# Some spherical harmonics

$$\begin{array}{l}
 Y_0^0 \\
 Y_{\pm 1}^1 \\
 Y_0^1 \\
 Y_{\pm 2}^2 \\
 Y_{\pm 1}^2 \\
 Y_0^2
 \end{array}
 \left| \begin{array}{l}
 \frac{1}{\sqrt{4\pi}} \\
 \sqrt{\left(\frac{3}{8\pi}\right)} e^{\pm i\phi} \sin \theta \\
 \sqrt{\left(\frac{3}{4\pi}\right)} \cos \theta \\
 \sqrt{\left(\frac{15}{32\pi}\right)} e^{\pm 2i\phi} \sin^2 \theta \\
 \mp \sqrt{\left(\frac{15}{8\pi}\right)} e^{\pm i\phi} \sin \theta \cos \theta \\
 \sqrt{\left(\frac{15}{16\pi}\right)} (3 \cos^2 \theta - 1)
 \end{array} \right|
 \left| \begin{array}{l}
 \sqrt{\left(\frac{3}{8\pi}\right)} (x \pm iy) \\
 \sqrt{\left(\frac{3}{4\pi}\right)} z \\
 \sqrt{\left(\frac{15}{32\pi}\right)} (x^2 \pm iy^2) \\
 \mp \sqrt{\left(\frac{15}{8\pi}\right)} z (x \pm iy) \\
 \sqrt{\left(\frac{15}{16\pi}\right)} (3z^2 - 1)
 \end{array} \right|$$

Complex conjugation :  $[Y_m^l(\theta, \phi)]^* = (-1)^m Y_{-m}^l(\theta, \phi)$ ,

Completeness :  $f(\theta, \phi) = \sum_{lm} f_{lm} Y_m^l(\theta, \phi)$ , where

$$f_{lm} = \int d\cos\theta d\phi [Y_m^l(\theta, \phi)]^* f(\theta, \phi).$$

# Legendre and Associated Legendre Polynomials

One often writes the spherical harmonics in the form

$$Y_m^l(\theta, \phi) = (-1)^m \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} e^{im\phi} P_l^m(\cos \theta),$$

where  $P_l^m(z)$  are called associated Legendre polynomials. From the recursion relations used before, one can find

$$P_l^m(z) = \frac{(-1)^l}{2^l l!} (1-z^2)^{m/2} \left( \frac{d}{dz} \right)^{l+m} (1-z^2)^l.$$

The Legendre polynomials are  $P_l(z) = P_l^0(z)$ . One can check that the Legendre polynomials are a complete set of orthogonal functions in the interval  $-1 \leq z \leq 1$ .



# A problem

- ➊ Starting from the trivial polynomial  $p_0(z) = 1/2$ , construct successively polynomials of successively higher orders which are orthogonal to all previously constructed polynomials. Does this process give the Legendre polynomials?
- ➋ Use Mathematica to construct arbitrary Legendre polynomials using the derivative expression given before.
- ➌ Check that they are orthonormal using Mathematica, and then prove that they are orthonormal.
- ➍ Plot successive  $P_l(z)$  and check that the zeroes of each  $P_l$  is bracketed by the zeroes of  $P_{l-1}$ .
- ➎ If the inner product on the Hilbert space of polynomials is changed to

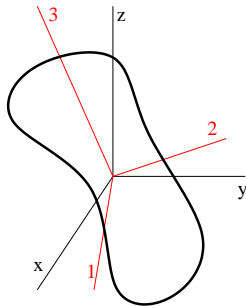
$$\langle f|g \rangle = \int_{-1}^1 dz w(z) f(z) g(z),$$

then the set of orthogonal polynomials changes. What weight function needs to be used to obtain the associated Legendre polynomials?

# Outline

- 1 Orbital angular momentum
- 2 The rigid rotor: a quantum top
- 3 References

# Operators and the Hamiltonian



The angular momentum of a top around its center of mass can be resolved into components along space fixed axes or along the principal axes of the body (body fixed axes),

$$\mathbf{L} = L_x \hat{x} + L_y \hat{y} + L_z \hat{z} = L_1 \hat{n}_1 + L_2 \hat{n}_2 + L_3 \hat{n}_3.$$

The Hamiltonian of the top is

$$H = \frac{L_1^2}{2I_1} + \frac{L_2^2}{2I_2} + \frac{L_3^2}{2I_3},$$

where  $I_j$  are the principal moments of inertia. The commutation relations of the space-fixed components of  $\mathbf{L}$  are  $[L_x, L_y] = i\hbar L_z$ , etc.. However, the commutation relations of the body-fixed components are  $[L_1, L_2] = -i\hbar L_3$ ,

# The meaning of commutators

Rotations about two different axes do not commute. One finds—

$$\begin{aligned}
 R_x(\phi_x)R_y(\phi_y) - R_y(\phi_y)R_x(\phi_x) \\
 &\simeq (1 + i\phi_x L_x/\hbar + \cdots)(1 + i\phi_y L_y/\hbar + \cdots) - \\
 &\quad (1 + i\phi_y L_y/\hbar + \cdots)(1 + i\phi_x L_x/\hbar + \cdots) \\
 &\simeq -i\phi_x\phi_y(L_x L_y - L_y L_x)/\hbar + \cdots \\
 &= 1 - R_z(\phi_x\phi_y) + \mathcal{O}(\phi^3).
 \end{aligned}$$

These manipulations start from the effect of rotations on quantum states. However, the fact that the difference of two rotations about different axes in opposite orders can be written as a third rotation can be seen even in classical mechanics (Goldstein).

# Rotations in body fixed axes

Now examine the commutator

$$R_1(\phi_1)R_2(\phi_2) - R_2(\phi_2)R_1(\phi_1),$$

in the configuration where the body fixed and space fixed axes coincide before the rotations are made. The first rotation can then be replaced by a space fixed rotation. So, for example, the first term above can be written as

$$R_1(\phi_1)R_y(\phi_2) = R_{x'}(\phi_1)R_y(\phi_2),$$

where we have used the fact that the axis about which the second rotation is performed changes as a result of the first. But a rotation about a changed axis can be related to that about the original axis through

$$R_{x'}(\phi_1) = R(\hat{x} \rightarrow \hat{x}')R_x(\phi_1)R^{-1}(\hat{x} \rightarrow \hat{x}').$$

By the argument above, one sees that  $R(\hat{x} \rightarrow \hat{x}') = R_y(\phi_2)$ .

# Commutation relations in body fixed axes

The previous arguments show that

$$R_1(\phi_1)R_y(\phi_2) = R_y(\phi_2)R_x(\phi_1)R_y^{-1}(\phi_2)R_y(\phi_2) = R_y(\phi_2)R_x(\phi_1).$$

The reversal of order also occurs in the second term, as a result of which the commutator reverses sign, and

$$R_1(\phi_1)R_2(\phi_2) - R_2(\phi_2)R_1(\phi_1) = R_3(\phi_1\phi_2) - 1 + \mathcal{O}(\phi^3).$$

One has  $R_3 = R_z$  in this formula, since the rotation  $R_3$  is applied in the original unrotated frame, *i.e.*, when the body fixed axes coincide with the space fixed axes. This shows that the commutation relations in the body fixed axes become

$$[L_j, L_k] = -i\hbar\epsilon_{jkl}L_l.$$

However, this change of sign in the commutator does not affect the spectrum of  $L_3$  and  $L^2$ . ([Check](#))

# Spectrum of a rigid rotor

When  $I_1 = I_2 = I_3$ , the Hamiltonian is

$$H = \frac{L^2}{2I}.$$

The eigenfunctions of this Hamiltonian are  $|j, m\rangle$ , and the eigenvalues are exactly those of  $L^2$ , i.e.,  $l(l+1)\hbar^2/2I$ . In the context of atomic spectra it is customary to introduce a *rotational constant*,  $B = \hbar/(4\pi I)$  and write  $E = Bh l(l+1)$ . There is a  $(2l+1)$ -fold degeneracy for each eigenstate. Successive energy levels are separated by  $\Delta E = 2Bh$ . Transitions between levels which are separated by  $\Delta l > 1$  are not allowed by *selection rules*. For a typical diatomic molecule, the reduced mass  $m \simeq (A/2)$  GeV, where  $A$  is the mass number of each atom. The separation between the nuclei is of the order of 0.1 nm. In these units  $\hbar \simeq 200$  eV nm. Hence,  $\Delta E \simeq (40000/10^8)$  eV, i.e.,  $\Delta E \simeq 10^{-4}$  eV.

# The symmetric quantum top

When  $I_1 = I_2 \neq I_3$ , one has a symmetric top. In this case,

$$H = \frac{L^2}{2I_1} + \left( \frac{1}{2I_3} - \frac{1}{2I_1} \right) L_3^2.$$

The Hamiltonian is no longer spherically symmetric, since  $[H, \mathbf{L}] \neq 0$ . However, the two terms can be simultaneously diagonalized, and the eigenfunctions of the Hamiltonian are precisely  $|l, m\rangle$  and that

$$E(l, m) = \hbar^2 \left[ \frac{l(l+1)}{2I_1} + \left( \frac{1}{2I_3} - \frac{1}{2I_1} \right) m^2 \right].$$

When  $I_1 < I_3$ , there are  $l$  doubly degenerate energy levels below a single level which coincides with that of the rigid rotor. For the case of  $I_1 > I_3$ , the  $m \neq 0$  levels all lie above that of the rigid rotor. Note also that the states  $|j, m\rangle$  and  $|j, -m\rangle$  can mix.



# Asymmetric quantum tops

For the asymmetric top, in which all three principal components of the inertia tensor are unequal, a general formula for the energy is not possible. However, since  $[H, L^2] = 0$ , one can diagonalize the Hamiltonian for each  $l$  separately. For  $l = 0$ , one finds that  $E = 0$ . For  $l = 1$ , the  $3 \times 3$  matrix to be diagonalized is

$$H = \frac{\hbar^2}{4} \begin{pmatrix} \frac{1}{I_1} + \frac{1}{I_2} + \frac{2}{I_3} & 0 & \frac{1}{I_1} - \frac{1}{I_2} \\ 0 & \frac{2}{I_1} + \frac{2}{I_2} & 0 \\ \frac{1}{I_1} - \frac{1}{I_2} & 0 & \frac{1}{I_1} + \frac{1}{I_2} + \frac{2}{I_3} \end{pmatrix}.$$

The eigenvalues of this matrix are easily found to be

$$E = \frac{\hbar^2}{2} \left( \frac{1}{I_1} + \frac{1}{I_2} \right), \quad \frac{\hbar^2}{2} \left( \frac{1}{I_1} + \frac{1}{I_3} \right), \quad \frac{\hbar^2}{2} \left( \frac{1}{I_2} + \frac{1}{I_3} \right),$$

with eigenvectors  $|1, 0\rangle$ ,  $|1, 1\rangle + |1, -1\rangle$  and  $|1, 1\rangle - |1, -1\rangle$  respectively.

# A problem

- 1 Construct the matrices which represent  $\mathbf{L}$  in the  $l = 2$  representation.
- 2 Solve the asymmetric top problem for  $l = 2$ .
- 3 The classical motion of a top can be described in terms of precession and nutation. Are such motions inherent in the solutions of the quantum asymmetric top problem?
- 4 Set up and solve the asymmetric top problem for  $j = 1/2$ . Interpret the results.
- 5 Does your interpretation correctly predict the behaviour of the asymmetric top for  $j = 3/2$ .

# Outline

- 1 Orbital angular momentum
- 2 The rigid rotor: a quantum top
- 3 References

# References

- ❶ Quantum Mechanics (Non-relativistic theory), by L. D. Landau and E. M. Lifschitz. The material in this lecture are scattered through chapters 4, 8 and 14 of this book.
- ❷ Quantum Mechanics (Vol 1), C. Cohen-Tannoudji, B. Diu and F. Laloë. Chapter 6 of this book discusses angular momentum. The presentation in these lectures follow this chapter sometimes.
- ❸ Classical Mechanics, J. Goldstein. The material on rotations in this book is a pre-requisite for understanding angular momenta in quantum mechanics.
- ❹ Discussion of the Rigid Rotator Problem, N. I. Greenberg, *Am. J. Phys.*, 45 (1977) 199–204. This article has a nice detailed and self-contained discussion of the quantum top.
- ❺ A Handbook of Mathematical Functions, by M. Abramowicz and I. A. Stegun. This is a handy place to look up useful things about various classes of functions.