

## Lecture 5

25/8/09

We have discussed the geodesic equation:

$$\ddot{x}^i + \Gamma_{jk}^i \dot{x}^j \dot{x}^k = 0$$

for a particle moving in curved space. Now we would like to discuss its spacetime version. We may guess it to be,

$$\ddot{x}^\mu + \Gamma_{\nu\lambda}^\mu \dot{x}^\nu \dot{x}^\lambda = 0$$

Now, however, we need to be more precise about its meaning. Since  $x^\mu = (t, x, y, z)$ ,  $x^0$  is the time. So what does  $\ddot{x}^\mu$  mean?

In fact  $\dot{x}^\mu = \frac{dx^\mu}{dT}$  where  $T$  is an arbitrary parameter along the world-line. This can make sense only if the equation is invariant under nonsingular arbitrary changes:  $T \rightarrow T'(T)$ , for which  $x'^\mu(T') = x^\mu(T)$ .

First we work in Minkowski spacetime:  $g_{\mu\nu}(x) = \eta_{\mu\nu}$ . To find the action from which the equation  $\ddot{x}^\mu = 0$  follows, let us note the following. The naive action

$$S = \int L d\tau \approx K \int dT \eta_{\mu\nu} \dot{x}^\mu \dot{x}^\nu \quad (K = \text{const})$$

is incorrect. It is not invariant under  $T \rightarrow T'(T)$ ,  $x'^\mu(T') = x^\mu(T)$ . Moreover,

$$p_\mu = \frac{dL}{d\dot{x}^\mu} = K \dot{x}_\mu \Rightarrow p^\mu p_\mu = K^2 \dot{x}^\mu \dot{x}_\mu$$

while we expect  $p^\mu p_\mu = m^2$  (fixed!)

Both problems are solved if we take the action

$$S = \int L d\tau = K \int d\tau \sqrt{-\eta^{\mu\nu} \dot{x}_\mu \dot{x}_\nu}$$

Under  $\tau \rightarrow \tau'(\tau)$ ,

$$d\tau' = \frac{d\tau'}{d\tau} d\tau$$

$$\frac{dx'^\mu}{d\tau'} = \frac{d\tau}{d\tau'} \frac{dx^\mu}{d\tau}$$

So  $S$  is indeed invariant. Moreover,

$$p_\mu = \frac{dL}{dx^\mu} = \frac{-K \dot{x}_\mu}{\sqrt{-\eta_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}}$$

$$\text{So } p^\mu p_\mu = K^2 \frac{\dot{x}^\mu \dot{x}_\mu}{(\sqrt{-\dot{x}^\alpha \dot{x}_\alpha})^2} = -K^2$$

We expect  $p^\mu p_\mu = -m^2$ , so  $K = \pm m$ . ~~the~~

We can even fix the sign. Using the reparametrization invariance of  $\tau$ , we can choose:

$$x^0 = \tau$$

and we have:

$$S = K \int d\tau \sqrt{-\eta^{00} - \eta^{ij} \dot{x}_i \dot{x}_j}$$

$$= K \int d\tau \sqrt{1 - \dot{x}_i \dot{x}^i} \sim -\frac{1}{2} K \dot{x}_i \dot{x}^i + \text{const.}$$

for low velocities  $\dot{x}^i$ . Thus  $K = -m$ .

So now let's look at the action

$$S = \int L d\tau = -m \int d\tau \sqrt{-\dot{x}^\mu \dot{x}_\mu}$$

Its equation of motion is

$$\frac{d}{d\tau} \frac{dL}{d\dot{x}^\mu} = 0 \Rightarrow \frac{\dot{x}^\mu}{\sqrt{-\dot{x}^\nu \dot{x}_\nu}} = 0 \Rightarrow \dot{x}^\mu = 0 \quad (\text{if } \dot{x}^\mu \dot{x}_\mu \neq 0).$$

Moreover  $p_\mu \equiv \frac{dL}{d\dot{x}^\mu} = \frac{m \dot{x}_\mu}{\sqrt{-\dot{x}^\nu \dot{x}_\nu}}$

In the "physical" gauge  $x^0 = \tau$  we have

$$\sqrt{-\dot{x}^\mu \dot{x}_\mu} = \sqrt{-\dot{x}^\nu \dot{x}_\nu} = \sqrt{1 - \vec{v}^2}$$

So  $E = \frac{m}{\sqrt{1 - \vec{v}^2}}$ ,  $\vec{p} = \frac{m\vec{v}}{\sqrt{1 - \vec{v}^2}}$  : familiar.

Note also that over a small interval  $d\tau$ , the length  $ds$  of the trajectory is

$$ds = \sqrt{-\eta_{\mu\nu} dx^\mu dx^\nu} = \sqrt{-\eta_{\mu\nu} \dot{x}^\mu \dot{x}^\nu d\tau^2}$$

so in fact  $S = -m \int d\tau \sqrt{-\dot{x}^\mu \dot{x}_\mu}$   
 $= -m \int \sqrt{-dx^\mu dx_\mu}$

and it's proportional to a geometric quantity: the invariant length of the trajectory.

we can imagine

|            |                     |
|------------|---------------------|
| $ds^2 > 0$ | (spacelike)         |
| $ds^2 = 0$ | (lightlike or null) |
| $ds^2 < 0$ | (timelike)          |

$$\begin{aligned} \text{Since } ds^2 &= -dt^2 + d\vec{x}^2 \\ &= dt^2 (-1 + (\frac{d\vec{x}}{dt})^2) = dt^2 (-1 + \vec{v}^2) \end{aligned}$$

we have (in  $c=1$  units)

|            |                 |                     |
|------------|-----------------|---------------------|
| spacelike: | $ \vec{v}  > 1$ | (faster than light) |
| lightlike: | $ \vec{v}  = 1$ |                     |
| timelike:  | $ \vec{v}  < 1$ |                     |

Physical, massive particles always follow a timelike trajectory.

With all these results, it is easy to guess the generalisation to a curved spacetime with metric  $g_{\mu\nu}(x)$ .

$$\text{we have: } ds^2 = -g_{\mu\nu} dx^\mu dx^\nu$$

$$\begin{aligned} \text{so } S &= \int d\tau L = \int d\tau ds \\ &= \int d\tau \sqrt{-g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu} \end{aligned}$$

It is instructive to consider the invariances of this action:

$$(i) \quad \left. \begin{aligned} T &\rightarrow T'(T) \\ g'_{\mu\nu}(x'(T)) &= g_{\mu\nu}(x(T)) \end{aligned} \right\} \begin{array}{l} \text{Re-parametrisation} \\ \text{of } T \end{array}$$

$$(ii) \quad \left. \begin{aligned} x^\mu &\rightarrow x'^\mu(x) \\ g_{\mu\nu} &\rightarrow g'_{\mu\nu}(x') = \frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial x^\beta}{\partial x'^\nu} g_{\alpha\beta}(x) \end{aligned} \right\} \begin{array}{l} \text{spacetime} \\ \text{reparametrisation} \\ \text{(coordinate} \\ \text{transformation)} \end{array}$$

What is the equation of motion for the action:

$$S = \int d\tau L = -m \int d\tau \sqrt{-g_{\mu\nu}(x) \dot{x}^\mu \dot{x}^\nu} \quad ?$$

We have:

$$\frac{\partial L}{\partial \dot{x}^\mu} = m \frac{g_{\mu\nu} \dot{x}^\nu}{\sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}}$$

$$\text{So } \frac{d}{d\tau} \left( \frac{g_{\mu\nu} \dot{x}^\nu}{\sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}} \right) = - \frac{\partial}{\partial x^\mu} \sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}$$

$$= \frac{g_{\alpha\beta, \mu} \dot{x}^\alpha \dot{x}^\beta}{2 \sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}}$$

$$\downarrow$$

$$\frac{g_{\mu\nu, \lambda} \dot{x}^\nu \dot{x}^\lambda + g_{\mu\nu} \ddot{x}^\nu}{\sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}} = \frac{-\frac{1}{2} g_{\nu\lambda, \mu} \dot{x}^\nu \dot{x}^\lambda}{\sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}}$$

$$= -g_{\mu\nu} \dot{x}^\nu \frac{d}{d\tau} \left( \frac{1}{\sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}} \right)$$

Thus  $\ddot{x}^\mu + \Gamma_{\nu\lambda}^\mu \dot{x}^\nu \dot{x}^\lambda = \cancel{g_{\mu\alpha}} \dot{x}^\mu \frac{d}{d\tau} \ln \sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta}$

This is not quite what we expected! However it is of the form

$$\ddot{x}^\mu + \Gamma_{\nu\lambda}^\mu \dot{x}^\nu \dot{x}^\lambda = f(x) \dot{x}^\mu$$

and we can always re-parametrize a curve to get rid of the R.H.S.

(Concretely, choose  $\tau'$  such that

$$\frac{d\tau'}{d\tau} = \cancel{\text{some}} \sqrt{-g_{\alpha\beta} \dot{x}^\alpha \dot{x}^\beta} \quad )$$

Then we finally get  $\ddot{x}^\mu + \Gamma_{\nu\lambda}^\mu \dot{x}^\nu \dot{x}^\lambda = 0$

Now we are only allowed reparametrizations for which

$$\frac{d^2\tau'}{d\tau'^2} = 0$$

(the class of  $\tau'$ 's related like this are called "affine parameters").

Examples of geodesics:

i) Sphere. Consider  $S^2$  with coords  $\theta, \varphi$ .

The metric is

$$ds^2 = R^2 (d\theta^2 + \cos^2 \theta d\varphi^2) \quad \begin{array}{l} -\frac{\pi}{2} \leq \theta \leq \frac{\pi}{2} \\ 0 \leq \varphi \leq 2\pi \end{array}$$

Calculate  $\Gamma$ 's:

$$\begin{aligned} \Gamma_{\theta\theta}^{\theta} &= \frac{1}{2} g^{\theta\theta} (g_{\theta\theta,\theta} + g_{\theta\theta,\theta} - g_{\theta\theta,\theta}) \\ &= 0. \end{aligned}$$

$$\begin{aligned} \Gamma_{\theta\varphi}^{\theta} &= \frac{1}{2} g^{\theta\theta} (g_{\theta\theta,\varphi} + g_{\theta\varphi,\theta} - g_{\theta\varphi,\theta}) \\ &= 0. \end{aligned}$$

$$\begin{aligned} \Gamma_{\varphi\varphi}^{\theta} &= \frac{1}{2} g^{\theta\theta} (g_{\theta\varphi,\varphi} + g_{\theta\varphi,\varphi} - g_{\varphi\varphi,\theta}) \\ &= -\frac{1}{2} g^{\theta\theta} g_{\varphi\varphi,\theta} \\ &= -\frac{1}{2} \cdot \frac{1}{R^2} \cdot R^2 \cdot 2 \sin \theta \cos \theta \\ &= -\frac{1}{2} \sin 2\theta \end{aligned}$$

$$\begin{aligned} \Gamma_{\theta\theta}^{\varphi} &= \frac{1}{2} g^{\varphi\varphi} (g_{\varphi\theta,\theta} + g_{\varphi\theta,\theta} - g_{\theta\theta,\varphi}) \\ &= 0 \end{aligned}$$

$$\begin{aligned} \Gamma_{\theta\varphi}^{\varphi} &= \frac{1}{2} g^{\varphi\varphi} (g_{\varphi\theta,\varphi} + g_{\varphi\varphi,\theta} - g_{\theta\varphi,\varphi}) \\ &= \frac{1}{2} \frac{1}{R^2 \cos^2 \theta} R^2 \cdot 2 \sin \theta \cos \theta = \tan \theta \end{aligned}$$

$$\Gamma_{\varphi\varphi}^{\varphi} = \frac{1}{2} g^{\varphi\varphi} (g_{\varphi\varphi,\varphi} + g_{\varphi\varphi,\varphi} - g_{\varphi\varphi,\varphi})$$

$$= \frac{1}{2} g^{\varphi\varphi} g_{\varphi\varphi,\varphi} = 0.$$

~~$$= \frac{1}{2} g^{\varphi\varphi} g_{\varphi\varphi,\varphi}$$~~

$$\text{So: } \ddot{\theta} + \Gamma_{\varphi\varphi}^{\theta} \dot{\varphi} \dot{\varphi} = 0$$

$$\ddot{\varphi} + 2\Gamma_{\theta\theta}^{\varphi} \dot{\theta} \dot{\varphi} = 0$$

$$\Rightarrow \ddot{\theta} - \frac{1}{2} \sin 2\theta (\dot{\varphi})^2 = 0$$

$$\ddot{\varphi} + 2 \tan \theta \dot{\theta} \dot{\varphi} = 0$$

Look for simple solns:

(i)  $\theta = \text{const.}$  Then  $\dot{\theta} = 0$  and:

$$\sin 2\theta \dot{\varphi}^2 = 0 = \ddot{\varphi}$$

$$\therefore \varphi = at + b \quad \text{and} \quad \theta = 0$$

(recall  $-\frac{\pi}{2} < \theta < \frac{\pi}{2}$ )

This is the equator!



(ii)  $\varphi = \text{const.}$  Now,

$$\ddot{\theta} = 0 \Rightarrow \theta = at + b \quad \text{at any } \varphi!$$

These are great circles of longitude.



(ii) spacetime. Consider

$$ds^2 = R^2 (-\cosh^2 \rho dt^2 + d\rho^2)$$

this space is called  $AdS_2$ . It is obtained from  $S^2$  by the  $\Theta = i\rho, R \rightarrow iR, \varphi = t, 0 \leq \rho \leq \infty$

It can be obtained by taking 2+1 d Minkowski spacetime:

$$ds^2 = \cancel{dt^2} = \cancel{dx^2 + dy^2} - (dx^0)^2 - (dx^1)^2 + \cancel{dx^2} + (dx^2)^2$$

and imposing:

$$(x^0)^2 + (x^1)^2 - (x^2)^2 \cancel{+ t^2 + x^2 + y^2} = R^2$$

The eqn is solved by:

$$x^0 = R \cosh \rho \cosh t$$

$$x^1 = R \cosh \rho \sinh t$$

$$x^2 = R \sinh \rho$$

and we get the above metric.

[We can also consider  $ds^2$ , given by starting with

$$ds^2 = \cancel{-(dx^0)^2} + (dx^1)^2 + \cancel{(dx^2)^2} (dx^2)^2$$

and imposing  $\cancel{x^2 + y^2} = \cancel{-t^2 + x^2 + y^2} = R^2$   
 $-(x^0)^2 + (x^1)^2 + (x^2)^2 = R^2$

(~~thus~~) we end up with:

$$ds^2 = R^2 (-dt^2 + \cosh^2 t d\rho^2) ]$$

Now

$$\begin{aligned}
 \Gamma_{tt}^p &= \frac{1}{2} g^{pp} (-g_{tt,p}) \\
 &= \frac{1}{2} \frac{1}{R^2} \cdot R^2 \cdot + (\cosh^2 p)' \\
 &= \cosh p \sinh p \\
 &= \frac{1}{2} \sinh 2p
 \end{aligned}$$

$$\begin{aligned}
 \Gamma_{pt}^t &= \frac{1}{2} g^{tt} (g_{tt,p}) \\
 &= \frac{1}{2} \frac{1}{-R^2 \cosh^2 p} \cdot R^2 \cdot - 2 \cosh p \sinh p \\
 &= \tanh p.
 \end{aligned}$$

Thus:

$$\ddot{p} + \frac{1}{2} \sinh 2p (\dot{t})^2 = 0$$

$$\ddot{t} + 2 \tanh p \dot{t} \dot{p} = 0$$

Thus we have the analogous geodesics:

(i)  $p = \text{const.}$  Then  $\ddot{t} = 0$  and  $\sinh p = 0$

So  $p = 0$  and  $t = a\tau + b$

(ii)  $t = \text{const.}$  Then  $\ddot{p} = 0 \Rightarrow p = a\tau + b$

The first geodesic is timelike

$$\begin{aligned}
 \left(\frac{ds}{d\tau}\right)^2 &= R^2 (-\cosh^2 p \dot{t}^2 + \dot{p}^2) \\
 &= -a^2 R^2 \cosh^2 p < 0 \Rightarrow \text{timelike}
 \end{aligned}$$

The second has  $\left(\frac{ds}{d\tau}\right)^2 = R^2 a^2 > 0 \Rightarrow \text{spacelike}.$

(iii) Rindler space in 2d.

$$ds^2 = -X^2 dT^2 + dX^2$$

Here  $\Gamma_{TX}^T = \frac{1}{X}$ ,  $\Gamma_{TT}^X = X$ , all others = 0.

The geodesics are:  $\ddot{X} + X \dot{T}^2 = 0$

$$\ddot{T} + \frac{2}{X} \dot{T} \dot{X} = 0$$

With  $X = 0$  (risky!) we find the timelike geodesics  $T = A\tau + B$ . Similarly with  $T = \text{const}$  we get spacelike geodesics  $X = A'\tau + B'$ .

It looks like  $X=0$  is a "bad point" (the time intervals shrink to zero size here!).

However, the transformation

$$T = \tanh^{-1} \frac{t}{x}, \quad X = \sqrt{x^2 - t^2}$$

$$t = X \sinh T, \quad x = X \cosh T$$

gives:

$$dT = \frac{x dt - t dx}{x^2 - t^2}$$

$$dX = \frac{x dx - t dt}{\sqrt{x^2 - t^2}}$$

So  $-X^2 dT^2 + dX^2$

$$= - (x^2 - t^2) \frac{(x dt - t dx)^2}{(x^2 - t^2)^2} + \frac{(x dx - t dt)^2}{x^2 - t^2}$$

$$\begin{aligned}
&= -\frac{1}{x^2-t^2} \left( x^2 dx^2 + t^2 dt^2 - 2xt dx dt \right. \\
&\quad \left. - x^2 dx^2 - t^2 dt^2 + 2xt dx dt \right) \\
&= -\frac{1}{x^2-t^2} \left( (x^2-t^2) dt^2 - (x^2-t^2) dx^2 \right) \\
&= -dt^2 + dx^2 \quad !
\end{aligned}$$

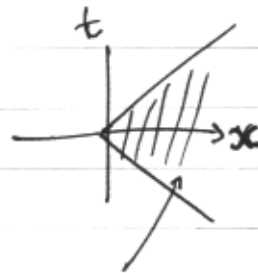
Thus (at least locally) Rindler space is equivalent to Minkowski space. These geodesics are trivial:

$$\ddot{x} = 0, \quad \ddot{t} = 0$$

This shows the power of coordinate transformation in finding geodesics more easily.

Note also that in Rindler space,  $0 < X < \infty$  and  $-\infty < T < \infty$  so:

$$\frac{t}{x} = \tanh T \Rightarrow -1 \leq \frac{t}{x} \leq 1$$



Also  $x^2 - t^2 = X^2 \Rightarrow -x \leq t \leq x$   
which is the same region: "Rindler wedge".

Also  $x \geq 0$  since  $x = X \cosh T$

We could have alternatively solved the geodesic eqns in Rindler coords by:

$$\ddot{T} + 2\dot{T}\frac{\dot{X}}{X} = 0$$

$$\Rightarrow \frac{d}{d\tau} \ln \dot{T} = - \frac{d}{d\tau} \ln X^2$$

$$\Rightarrow \dot{T} = \frac{A}{X^2}$$

$$\text{Next, } \ddot{X} + X\dot{T}^2 = 0 \Rightarrow \ddot{X} + \frac{XA^2}{X^4} = 0$$

$$\Rightarrow \dot{X}\ddot{X} + \frac{\dot{X}A^2}{X^3} = 0$$

$$\Rightarrow \dot{X}^2 = \frac{A^2}{X^2} + \text{const.}$$